

Schedule

Day1

- **Lecture 1: 1 hr (PS)**

Short introduction to matrix inversion and generalized matrix inversion. Particularly the introduction of the Moore-Penrose, weighted Moore-Penrose, Drazin, and Group inverse, $\{i,j,k\}$ inverses, inner inverses, and outer inverses with prescribed range and null space. Least squares solutions and best approximate solution.

- **Lecture 2: 1 hr (PS)**

Definitions of gradient and Hessian, matrix and vector norms. Basic principles and methods in nonlinear unconstrained optimization, overview of line search methods. Overview of gradient descent methods, Newton method and quasi-Newton methods, conjugate gradient nonlinear optimization methods.

- **Lecture 3: 1 hr (SSA)**

Matrix decompositions, Singular Value Decomposition (SVD), Moore Penrose Inverse, computation of condition numbers of a matrix.

Day 2

- **Lecture 4: 1 hr (PS)**

Recurrent Neural Networks (RNN), Continuous-time RNN, Gradient Neural Networks (GNN), GNN dynamics for solving linear matrix equations $AXB=C$, GNN for computing generalized inverses of constant matrices, GNN for solving systems of linear equations.

- **Tutorial 1: 2 hr (PS)**

Simulink as an efficient tool for agile software development. Simulink implementation of GNN for solving the general linear matrix equations $AXB=C$. Simulink for GNN design for computing the matrix inverse, left and right inverse and the Moore-Penrose generalized inverse. Simulink implementation of GNN models for solving systems of linear equations.

- **Lecture 5: 1 hr (SSA)**

Computation of SVD, computation of condition numbers, solving least square problems using SVD.

Day 3

- **Lecture 6: 1 hr (PS)**

Design parameters in GNN evolutionary design. Properties of activation functions in RNN, overview of commonly used activation functions (AFs): linear, bipolar sigmoid,

power AF, power-sigmoid, hyperbolic sine, sign-bi-power, tunable AF. Influence of gain parameters and activations functions on the convergence speed.

- **Lecture 7: 1 hr (SSA)**
LU and its Sensitivity analysis. Pivoting, matrix rank, matrix range and null space.
- **Tutorial 2: 2 hrs (SSA)**
Computations of LU and solving systems of equations using forward and backward substitutions.

Day 4

- **Lecture 8: 1 hr (PS)**
Basic principles of Zhang Neural Networks (ZNN), scalar-valued, vector-valued and matrix-valued error function for time-varying inversion.
- **Lecture 9: 1 hr (PS)**
Development of ZNN models for solving time-varying scalar-valued reciprocal, vector-valued models for solving systems of linear equations, matrix-valued and matrix-valued time-varying inversion. ZNN for solving over-determined and under-determined systems of linear equations.
- **Tutorial 3: 2 hrs (PS)**
Implementation of nonlinear GNN and ZNN models based on various activation functions. Numerical experiments and comparison of obtained results regarding influence of the gain parameter and AFs.

Day 5

- **Lecture 10: 1 hr (PS)**
Solving time-varying inversion problems using scalar-valued, vector-valued and matrix-valued error functions. Computing time-varying generalized inverses.
- **Lecture 11: 1 hr (SSA)**
QR matrix decomposition and its application to solve least square problems, minimum norm least square solution.
- **Tutorial 4: 2 hrs (SSA)**
Computation of Reflectors, and rotators, to solve least squares problems using QR factorizations.

Day 6

- **Lecture 12: 1 hr (PS)**
Application of ZNN in solving time-varying linear matrix equations $AXB=C$ and systems of linear equations $Ax=b$.
- **Lecture 13: 1 hr (PS)**
Application of ZNN in solving time-varying linear matrix equations $AXB=C$, Lyapunov equation $AX+XAT+Q=0$, Sylvester equation $AX+XB=C$ and non-symmetric algebraic Riccati equation $DX+XAXBX+Q=0$.
- **Tutorial 5: 2 hrs (PS)**
Implementation of ZNN models for solving various time-varying matrix equations. Applications in computing generalized inverses and solving linear systems.

Day 7

- **Lecture 14: 1 hr (PS)**
Correlations between GNN and gradient descent methods of unconstrained nonlinear optimization. Newton iteration for matrix inversion as discretized ZNN continuous-time dynamics. Modifications of GNN and ZNN dynamics arising from gradient and Newton optimization methods.
- **Lecture 15: 1 hr (PS)**
Survey about nonlinear activations. Overview of main activation functions which enable finite time and predefined time convergence. Finite-time and predefined-time convergence analysis of ZNN design.
- **Lecture 16: 1 hr (PS)**
Development of ZNN models for solving scalar-valued and matrix-valued time-varying inversion and generalized inversion.

Day 8

- **Lecture 17: 1 hr (PS)**
Implementation of finite-time ZNN models. Experiments on finite time convergent ZNN dynamical systems and comparison of various activations.
- **Lecture 18: 1 hr (PS)**
Application of ZNN in approximating time-varying square root, inverse square root, constrained matrix equations and various matrix functions.

- **Lecture 19: 1 hr (PS)**

Overview of activation functions in RNN, survey on nonlinear activations. Finite-time and predefinedtime convergent ZNN based on nonlinear AFs. Finite-time ZNN design.

Day 9

- **Lecture 20: 1 hr (PS)**

Existence and representations of solutions to some constrained matrix equations and systems of matrix equations. Computation of various generalized inverses arising from corresponding systems of matrix equations.

- **Tutorial 6: 2 hrs (SSA)**

Computation of Eigenvalues by using Raleigh Quotient shifts and Wilkinson Shifts.

- **Lecture 21: 1 hr (PS)**

Modified ZNN dynamical systems, ZNN based on optimization method, ZNN models based on iterative methods, ZNN dynamical systems based on fuzzy and neutrosophic logic systems.

Day 10

- **Lecture 22: 1 hr (PS)**

RNNs for solving linear inequalities and equations, RNNs for generating LU decomposition, QR decomposition and Cholesky factorization.

- **Lecture 23: 1 hr (SSA)**

QR-Algorithm for computing Eigenvalues.

- **Lecture 24: 1 hr (PS)**

Applications of ZNN neural design in mobile object localization, time-varying nonlinear equations solving. Discussion about possibilities for further research.